

Recap Decidable problems for PN

BOUNDEDNESS is $\mathcal{Q}(N)$ finite

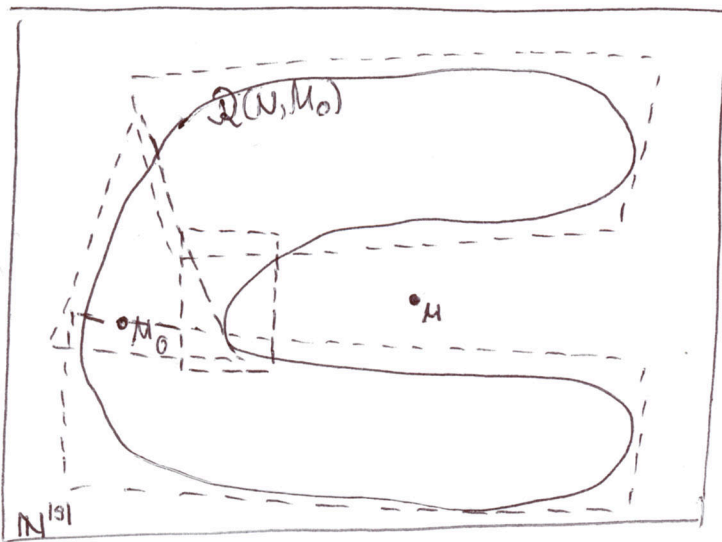
TERMINATION is $\mathcal{Q}(N)$ acyclic

COVERABILITY is $M \in \mathcal{Q}(N) \downarrow$
 $\left. \begin{array}{l} \rightarrow \text{K\&M non prim rec} \\ \rightarrow \text{Rackoff in EXSPACE} \\ \rightarrow \text{Lipton EXSPACE-hard} \end{array} \right\} \text{EXSPACE -complete}$

REACHABILITY is $M \in \mathcal{Q}(N)$ DECIDABLE!

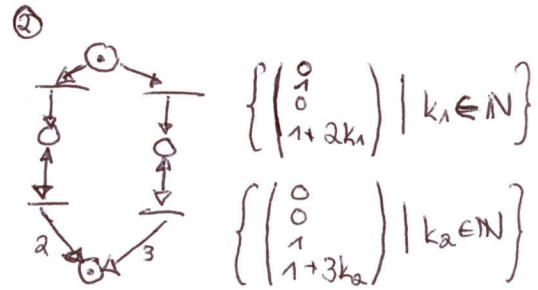
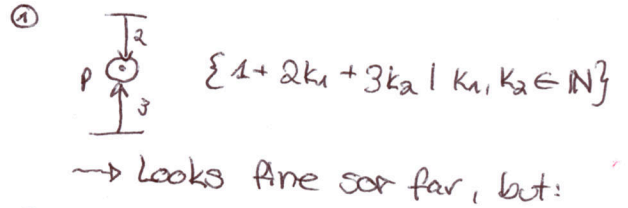
REACHABILITY is $M \in \mathcal{Q}(N)$

- Incomplete proof \rightarrow Sacerdote & Terney
- First proof \rightarrow Mayr 1981
 \rightarrow algo had NON PRIM REC complexity
- First simplification \rightarrow Kasaravv 1982
- Further simplification \rightarrow Lambert 10 years later
 \rightarrow Leroux 2009
 \rightarrow Leroux & Schmitz 2015

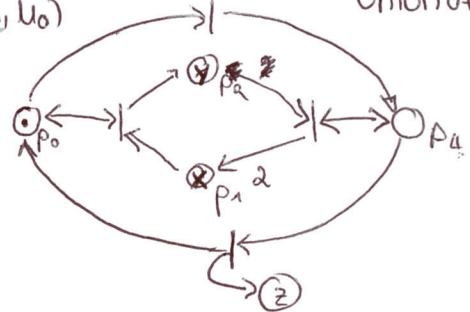


- ① We want to overapprox $\mathcal{R}(N, M_0)$
- ② Linear ineq are not enough to separate $\mathcal{R}(N, M_0)$ from M (unreach)
 \rightarrow source of incompleteness
- ③ Finite unions of linear sets make the approach complete

Example



③ 5-place Petri-net not representable by union of linear sets (N, M_0)



$$\mathcal{R}(N, M_0) = \{ (1 \ x \ y \ z \ 0) \mid 0 < x + y \leq 2^z \} \cup \{ (0 \ x \ y \ z \ 1) \mid 0 < 2y + x \leq 2^z \}$$

Def Let $\vec{p} = p_0, \dots, p_n$ be vectors in \mathbb{N}^k . Define

$$\mathcal{L}[\vec{p}] := \{ p_0 + k_1 p_1 + \dots + k_n p_n \mid k_i \in \mathbb{N} \}$$

A subset $X \subseteq \mathbb{N}^k$ is called LINEAR if there is \vec{p} s.th. $X = \mathcal{L}[\vec{p}]$

A subset of \mathbb{N}^k is called SEUILINEAR if it is a finite union of linear sets

Thm ① For all PN with $|S| < 5$. $\mathcal{R}(N, M_0)$ is semilinear.

② there are PN with $|S| = 5$ where $\mathcal{R}(N, M_0)$ is NOT semilinear

Def Let $N = (S, T, W)$ be a PN. A set $X \subseteq \mathbb{N}^{|S|}$ is a forward inductive invariant if $\forall M \in X \forall t \in T M \xrightarrow{t} M' \Rightarrow M' \in X$

Example Let $I \in \mathbb{Z}^{|S|}$ be structural invariant ($I^T C = 0$) and $k \in \mathbb{Z}$.

$$A_{I, k} = \{M \in \mathbb{N}^{|S|} \mid I^T M = k\}$$

is called forward inductive invariant

Lemma Let X be a fwd. ind. inv. for a PN N then $\mathcal{R}(N, M_0) \subseteq X$ iff $M_0 \in X$ i.e. fwd ind inv containing M_0 is an overapproximation of $\mathcal{R}(N, M_0)$

Example $I^T M \neq I^T M_0 \Rightarrow M \notin \mathcal{R}(N, M_0)$ can be represented as

$$M \notin A_{I, I^T M_0} \Rightarrow M \notin \mathcal{R}(N, M_0)$$

MAIN RESULT (Lenz)

Let $M \notin \mathcal{R}(N, M_0)$ then $\exists A \subseteq \mathbb{N}^{|S|}$ semilinear and fwd. ind. inv. s.t. $M_0 \in A$ and $M \notin A$

Algorithm for $M \in \mathcal{R}(N, M_0)$

Run two semi algorithms in parallel as PA formula ψ_A

- ① Enumerate semilinear sets A and check
 - a) A fwd ind inv \Leftrightarrow Check ψ_A is sat
 - b) $M_0 \in A$
 - c) $M \notin A$
- \rightarrow terminates if $M \in \mathcal{R}(N, M_0)$

- ② Enumerate runs trying to find $M_0 \xrightarrow{\sigma} M$
- \rightarrow terminates if $M \in \mathcal{R}(N, M_0)$

Def Presburger Arithmetic FO theory over $(\mathbb{N}, +, \leq)$

$$\rightarrow \forall x, y = x + z, x \leq y, x \equiv_k y$$

Def $X \subseteq \mathbb{N}^k$ is PA-definable if \exists formula in PA with k free var so that

$$X = \left\{ \left(\begin{matrix} I(x_1) \\ \vdots \\ I(x_k) \end{matrix} \right) \mid I \models \varphi(\vec{x}) \right\}$$

Fact:

- ① X is semilinear $\Leftrightarrow X$ is PA-definable
- ② Satisfiability for PA is decidable

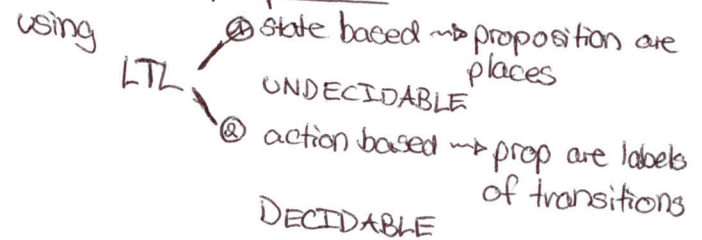
Construction

Given $\varphi(\vec{x})$ as PA formula, we constr. a PA formula ψ that is sat iff φ describes a fwd ind. inv.

$$\psi \equiv \forall M \in \mathbb{N}^{|S|} \forall M' \in \mathbb{N}^{|S|} : (\varphi(M) \wedge \bigvee_{t \in T} M \xrightarrow{t} M') \Rightarrow \varphi(M')$$

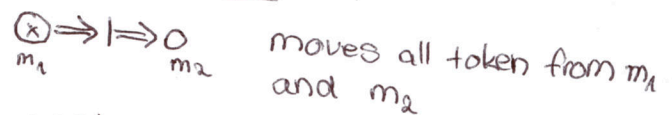
$\downarrow \forall m_1 \dots \forall m_k$ $\downarrow m_1 \geq 1 \wedge m'_2 = m_2 + 2$

Liveness properties



Extensions of Petri nets

① transfer arcs



② reset arcs



③ zero tests



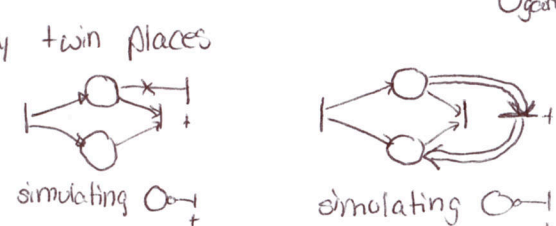
\rightarrow all problem undecidable

For ① and ② some decidable

Overview

	PN	TN	RN	IN
TERMINATION	D	D [⊙]	D [⊙]	U
REACHABILITY	D	U	U	U ← ⊙
BOUNDEDNESS	D	D [⊙]	U [⊙]	U
PLACE BOUNDEDNESS	D [⊙]	U	U	U
COVERABILITY	D	D	D	U

- ⊙ by KM
- ⊙ by exercise extending algo for PN
- ⊙ by garbage place $O \xrightarrow{*} I \mapsto O \Rightarrow O_{garbage}$



⊙ by red of Diophantine eqs

Note by ⊕ Cov for TN, RN cannot be done by adapting K&U

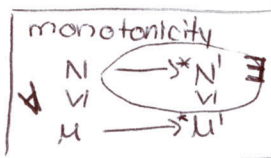
Note PN + 1 inhibitor arc have decidable coverability

Def QOTS (S, \rightarrow, \leq) quasi ordered transition system

- ⊙ S set of configurations (typically infinite)
- ⊙ $\rightarrow \subseteq S \times S$ transition relation
- ⊙ $\leq \subseteq S \times S$ wqo

To replace the termination algorithm from PN we need

- ⊙ finite branching
- ⊙ monotonicity
- ⊙ (S, \leq) is wqo



Def Well Structured Transition Systems (WSTS) is a QOTS (S, \rightarrow, \leq) such that

- ⊙ (S, \leq) is wqo
- ⊙ \leq is a simulation: $\forall s_1 \leq t_1$ and $s_1 \rightarrow s_2$, $\exists t_2: t_1 \rightarrow t_2 \geq s_2$

- ⊙ = * weak simulation
- ⊙ = + transitive simulation

Def Let $s_0 \in S$. $FRT(s_0)$ (Finite reach tree from s_0) is a S -labelled directed tree so that

- ⊙ root n_0 is labelled by s_0
 - ⊙ n has a child for each transition $s \rightarrow t_i$ if $\exists n'$ in the path from n_0 to n that is labelled with s' s.t. $s' \leq s$ otherwise n has no child
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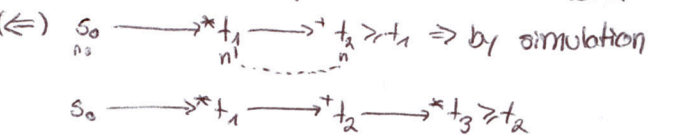
Note: $s, s', t_1, \dots, t_k \in S \rightarrow$ labels, n, n', n_0, \dots, n_k nodes

Lemma $FRT(s)$ is finite for every finitely branching WSTS.

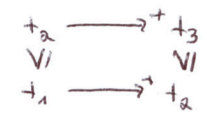
Proof by König's lemma: if $FRT(s)$ is inf, it contains an infinite path. By wqo \leq such an infinite path would contain a subsumed node. But that node has no successor by construction.

Lemma (S, \rightarrow, \leq) has a non terminating computation tree from $s_0 \in S$ if and only if $FRT(s_0)$ contains a subsumed node.

Proof (\Rightarrow) let π be infinite computation from s_0 then $\pi = \pi_1 \pi_2$, π_1 finite labelling a path from the root of $FRT(s_0)$. Since the last node in this path is a leaf, and has no successors (by $\exists \pi$) so n is missed.



In other words



obtain an infinite computation $t_1 \xrightarrow{+} t_2$

Thm TERMINATION is decidable for finitely branching transitive WSTS.